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#### **Abstract**

In this study, a two phase hybrid heuristic approach was proposed to solve the multi-depot multi-vehicle inventory routing problem (MDMVIRP). Inventory routing problem (IRP) is one of the major issues in the supply chain networks that arise in the context of vendor managed systems (VMI) The MDMVIRP combines inventory management and routing decision. We are given on input a fleet of homogeneous vehicles, in which any of these vehicles have a capacity and a fixed cost. Also, a set of distribution centers with restricted capacities are responsible to serve the customer's demands, which are known for distributer at beginning of each period. The problem consists of determining the delivery quantity to the customers at each period and the routes to be performed to satisfy the demand of the customers. The objective function of this problem is to minimize sum of the holding cost at distributer centers and the customers, and of the transportation costs associated to the preformed routes. In the proposed hybrid heuristic method, after a Construction phase (first phase) a modified variable neighborhood search algorithm (VNS), with distinct neighborhood structures, is used during the improvement phase (second phase). Moreover, we use simulated annealing (SA) concept to avoid that the solution remains in a local optimum for a given number of iterations. Computational results on benchmark instances that adopt from the literature of IRP indicate that the proposed algorithm is capable to find, within reasonable computing time, several solutions gained by the approaches that applied in the previous published studies.

Keywords: Inventory-routing problem, variable neighborhood search, two-phase heuristic

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#### 1. Introduction

Collaboration between all supply chain partners is one of the most important strategies for obtaining competitive advantage. Vendor managed inventory (VMI) system deals with collaboration between a distributer and customers [Hosseini-Motlagh et al. 2015]. Under VMI policy, the distributer decides on the order quantity and products delivery time to the vendor takes customers. Also the responsibility for determining the inventory level of its customers to prevent any shortage. This approach is often defined as a win-win situation for the supplier and its customers in which suppliers can reduce total cost considerably including distribution and holding costs by integrating transportation decisions between different customers. In addition, retailers do not assign the resources to inventory control.

In the literature, the problem in which transportation and inventory management decisions are integrated simultaneously is called the inventory routing problem (IRP) that is classified in the context of VMI systems. Under this strategy, the vendor is free to decide on how much to deliver to its customers and when to visit each of them. In other words, the vendor guarantees that stock out cannot occur on its customers' side during the time horizon. In the last decade, IRP has received much attention in this research area. There are many applications for IRP in a wide variety of industries such as food distribution, perishable items[Saremi et al. 2015] [Majidi et al. 2015; Hosseini-Motlagh et al. 2017; Majidi et al. 2017], blood[Jokar and Hosseini-Motlagh, 2015; Cheraghi and Hosseini-Motlagh, 2017] and [Jokar and Hosseini Motlagh, 2015], waste organic oil, pharmaceutic Items [Riahi et al., 2013], fuel and automobile components.

One of the first studies on IRP was done by [Bell et al.1998]. Since then, several variants of IRP have been described in the literature, mainly depending on the number of depots (one or multiple), the number of vehicles to visit all

customers (one versus multiple), the nature of the demand function involved (deterministic or stochastic) and the length of the time horizon (finite versus infinite). See for more details [Anderson et al. 2010] and [Coelho et al. 2013].

In the field of exact methods, the first branch and cut algorithm was proposed by [Archetti et al. 2007] for the basic IRP (with a single depot and a single vehicle). Later, it was improved by [Solyalı and Süral, 2011] who used a stronger formulation and a heuristic method to obtain an initial upper bound for the branch and cut algorithm. [Coelho and Laporte, 2013] and [Adulyasak et. al, 2013] introduced an extension of the formulation in [Archetti et al. 2007] for multiple vehicles IRP and solved it by the branch-and-cut algorithm.

The multi-depot multi-vehicle inventory routing problem (MDMVIRP) is classified as an NP-hard problem since this problem originates from VRP and it is known as an NP-hard problem in the literature. Thus reaching the optimal (or nearoptimal) solution is computationally expensive, several heuristic approaches are proposed to achieve good solutions within an acceptable computing time. [Huang and lin, 2010] considered a multi-item IRP with stochastic customers' demand. They proposed a modified ant colony algorithm which aimed at minimizing the total travel length. [Liu and Lee, 2011] introduced a two-phase variable neighborhood tabu search algorithm for IRP with time windows constraints. In the proposed method, the initial solution was constructed in the first phase and improved by a proposed heuristic method through the second phase. [Cordeau et al. 2015] introduced a three-phase heuristic procedure for multi-product IRP. In the first phase, a lagrangian-based method was used to determine the replenishment plans. The sequencing of the planned delivery is determined in the second phase and finally, in the third phase, a heuristic search algorithm was proposed to gain a better solution for the integrated problem. [Mirzaei and Seifi, 2015] developed an efficient heuristic algorithm for perishable IRP in which the cost of lost sales is considered as a non-linear and linear

function of the inventory age. [Shabani and Nakhai,2016] introduced an efficient population-based simulated annealing algorithm (PBSA) for Periodic IRP with multiple products. They compared the computational results of the proposed algorithm with simulated annealing (SA) and genetic algorithm (GA).

Our Inventory routing problem literature review researches indicate the leakage of studies in which, the advantage of multiple distribution centers are considered.

[Soysal et al. 2016] proposed the multi-depot IRP for perishable products in the food logistics systems. However, they have only solved the problem with the limited number of customers and depots. In this paper, the IRP model with the advantage of considering multiple distribution centers is enhanced and an effective algorithm for solving the problem at the more reasonable time in the large scales is proposed consequently. Therefore, a multi-depot multi - vehicle IRP problem (MDMVIRP) in which customers' demands are known at the beginning of the time horizon is considered and Moreover, a two-phase heuristic method based on variable neighborhood Search and simulated annealing, which we refer as a two-phase VNS-SA is proposed in this article. Further parts of the paper is organized as follows. Section two is devoted to the mathematical model. The heuristic algorithm is propsed in section 3 and Comprehensive computational results are presented in Section 4. Finally, conclusions and future research directions are provided in section 5.

## 2. Problem Description

A mixed-integer linear programming model for the multi-depot, multi-vehicle Inventory Routing problem is addressed in this section. As indicated in (Coelho et al. 2012), it is possible to modify this formulation in order to consider the multidepot option. This problem is defined on a graph G = (N, E)where N = $\{1, \dots, |n|, \dots, |m+n|\}$  is composed of the vertex set N in which the nodes  $\{1,...,n\}$  represent suppliers (depots) and the remaining nodes denote the retailers and  $E\{(i,j): i,j \in N, i \neq j\}$  is the set of arcs. Meanwhile, in the following we abbreviation  $E(S) = \{(i, j) \in E : i \in A\}$  $S, j \in S$  in which the notation S represents arbitrary node set. Moreover  $\{d_1d_2\}$  are an arbitrary subset of depot set. The storage capacity of all retailers is limited. Furthermore, the demand of all retailers is assumed to be known over all periods.

#### Sets

R	Retailers' set
D	Set of depots
N	Set of all points $(R \cup D)$
T	Set of time periods
K	Set of vehicles

#### **Parameters**

$c_{ij}$	Travel cost from retailer/depot $i$ to retailer/depot $j$ $i \in N, j \in N$ ; satisfying triangular
,	inequality; $c_{ik} + c_{kj} \ge c_{ij}$
$h_{it}$	Holding cost in period $t$ per unit for $i \in R$
$r_{it}$	Demand of retailer $i$ in period $t$ for $t \in T$ , $i \in R$
$\acute{r}_{it}$	available product at depot $i \in D$ in period $T$
$U_i$	Storage capacity of retailer <i>i</i>

 $U_i$ Storage capacity of depot i Vehicle capacity initial inventory level of customer i  $I_{i,0}$ Variables 1 if vehicle k along arc(i, j)  $i \in N, j \in N$  and originating from depot d and otherwise, 0 1, if vehicle k originating from depot d visits point i in period t and otherwise,0 Inventory amount of node (supplier or retailer) i in period t The delivered amount to retailer i by vehicle k originating from depot d in period t inventory amount of depot d in period t  $Min = \sum_{i \in N} \sum_{t \in T} h_{it} I_{it} \sum_{i,j \in R} \sum_{t \in T} \sum_{d \in D} \sum_{k \in K} c_{ij} y_{ijd}^{kt}$ (1)  $I_{dt}^{'} = I_{d,t-1}^{'} + \dot{r}_{dt} - \sum_{k \in K} \sum_{i \in \hat{R}} q_{id}^{kt}$  $\forall t \in T, \forall d$ (2)  $I_{it} = I_{i,t-1} - r_{it} + \sum_{k \in K} \sum_{d \in D} q_{id}^{kt}$  $\forall i \in R, t \in T$ , (3)  $\forall i \in N, t \in T$ (4)  $\sum_{k \in K} q_{id}^{kt} \ge U_i \sum_{k \in K} z_{it}^k - I_{i,t-1}$  $\forall i \in R, t \in T$ (5)  $\sum_{\substack{k \in K \\ d \in D}} \sum_{\substack{d \in D}} q_{id}^{kt} \leq U_i - I_{i,t-1}$  $q_{id}^{tk} \leq U_i z_{id}^{tk}$  $\forall i \in R, t \in T$ (6) $\forall i \in R, d \in D, t \in T, k \in K$ (7)  $\sum_{i}\sum_{t}q_{id}^{kt}\leq Q_{k}$  $\forall t \in T, k \in K$ (8) $\sum_{k \in \mathcal{K}} \sum_{d \in \mathcal{D}} \sum_{i \in \mathcal{D}} y_{ijd}^{kt} \le 1$  $\forall i \in R, t \in T$ (9) $\sum_{i:(i,i)\in F} y_{ijd}^{kt} = 2z_{id}^{tk}$  $\forall i \in N, d \in D, t \in T, k \in K$ (10) $\sum_{\substack{j:(i,j)\in E(S)\\z_{id}^{tk}\in\{0,1\}}}y_{ij}^{kt}\leq\sum_{i\in S}z_{id}^{tk}-z_{sd}^{tk}$  $s \subseteq \hat{N}, s \in S, k \in K, t \in T$ (11) $\forall i \in N, t \in T, d \in D, k \in K$ (12) $\sum_{\substack{k \in K \\ y_{ijd}^{kt}}} \sum_{\substack{d \in D \\ i \in R}} y_{ijd}^{kt} \leq 1$  $\forall j \in R, t \in T$ (13) $\{i,j\} \in E \ t \in T, d \in D, k \in K$ (14) $y_{d1id2}^{kt} = 0$  $\forall d \in D, t \in T, k \in K, \forall j \in N$ (15) $y_{id1d2}^{kt} = 0$  $\forall d \in D, t \in T, k \in K, \forall j \in N$ (16) $q_{id}^{kt} \ge 0$  $\forall i \in R, t \in T, d \in D, k \in K$ (17)

In this model, the aim of the objective function (1) is to minimize the total cost including inventory and transportation costs. The inventory levels for both the suppliers and the retailers at the end of period t are defined by constraints (2) and (3). Constraints (4) induce the absence of shortage at the suppliers and the retailers' sides. Constraints (5) and (6) ensure that if customer i is visited in period t, the delivered quantity does not exceed the customer's inventory capacity. Constraints (7) limit the available production in each depot. Constraints (8) ensure that the demand amounts must not exceed the vehicle's capacities. Constraints (9) – (11) are the routing constraints. Constraints (12) - (14) define the type of decision variables. Constraints (15) and (16) institute that there is no arc from depots or customers to itself consequently using any type of vehicles. Constraints (17) ensure that at most one vehicle type originating from a given depot can meet customerj.

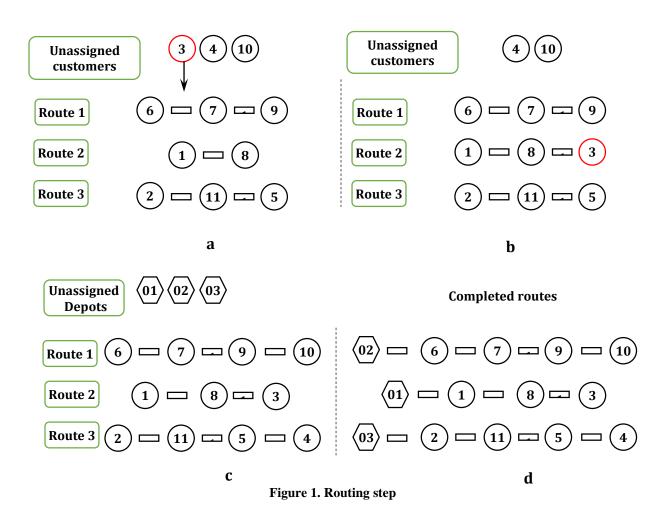
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End

# 3. Proposed Method: Two-phase VNS-SA for the MDMVIRP

The variable neighborhood search (VNS) algorithm, as a meta-heuristic method, was developed by [Mladenović & Hansen, 1997]. The basic idea is to change neighborhood systematically within a local search algorithm. This implies that several neighborhoods are used to search for the solution improvement. In this paper, we propose a two-phase heuristic method based on VNS and SA algorithms to solve MDMVIRP, namely the two-phase VNS-SA method. As it can be seen in Algorithm 1, in the first phase, an initial solution is made through a constructive heuristic method. Then, the initial solution will be improved by modified VNS method. The two phases are described in the following

```
Algorithm 1.
                       General structure of the proposed method
      Start
2
      Generate Initial solution (first phase)
3
          Repeat (second phase)
4
            Update T
5
            Loop (VNS structure)
6
               Set k \leftarrow 1:
7
               Generate a neighbor solution \dot{x} from the k<sup>th</sup> structure of x
8
               Compute \Delta = f(x) - f(x) and generate r (random number between (0,1))
               If (\Delta < 0) or (e^{-\Delta/T} > r) then (x \leftarrow \acute{x}), set k \leftarrow 1; otherwise set k \leftarrow k + 1;
9
            End loop (until k = k_{max})
10
11
            Loop (Local search structure)
               Set l \leftarrow 1;
12
13
               Generate a neighbor solution \dot{x} from a random local search of x
               Compute \Delta = f(x) - f(x) and generate r (random number between (0,1))
14
              If (\Delta < 0) or (e^{-\Delta/T} > r) then (x \leftarrow \acute{x})
15
               Set l \leftarrow l + 1
16
            End loop (until l = l_{max})
17
18
          Until stop condition
```



# **3.1.** Phase 1: Construction of Initial Solution (IS)

, this phase is divided into two steps, In order to gain the IS. In the first step, a heuristic method is performed to solve a capacitated vehicle routing problem period by period. It means that, in this step, inventory decisions will not be taken into consideration. In the second one, we propose a heuristic procedure that can be used to improve the IS, which is generated in the previous step, by considering the inventory aspect of the problem. In the heuristic procedure, in a certain period t, a visited retailer will be removed from the

route if it results in reducing the total cost. It is important to note that the amounts of quantity of the retailers' demands had to be satisfied in the previous period. The procedure is repeated until no more improvement is possible.

#### **Routing step:**

First of all, this step starts by building a certain number of empty routes based on the number of the available vehicles. Then, unassigned customers are selected one by one (**Fig. 1a**) and inserted into the feasible route with lower cost (**Fig. 1b**). After that, each route is assigned to the closest depot with

enough residual capacity (**Fig. 1c** and **Fig. 1d**)., the heuristic approach is repeated, For each period.

#### 3.2. Phase 2: Improvement Phase

The initial solution of the first phase is improved by the proposed heuristic method. In the second phase, our proposed scheme is composed of two parts. At first, a modified variable neighborhood search algorithm is used to improve the solution by using a set of neighborhood structures then, a local search algorithm is used to escape from the local optimality. In all over of this phase, the new neighborhood solution will be accepted after being compared with the current solution. This acceptance mechanism is based on the simulated annealing acceptance criteria. The heuristic procedure details are described as follow:

#### **Modified Variable Neighborhood Search**

The VNS begins with the initial solution and tries to iteratively improve the current solution and reach a better neighboring solution by using several neighborhood structures. In our implementation, the neighborhood is started with a first improvement strategy and the algorithm will terminate if no better solution is found. We use six different neighborhood structures within the space of the solution. In this

section, we propose a new combination of using these neighborhood structures in the context of Inventory routing problem. Meanwhile, we introduce 2 new structures ( $E_5$  and  $E_6$ ) which have not already applied in the literature. Notably, these combinations have not existed in the literature of inventory routing problems.

#### **Reposition Neighborhood (E1)**

In this structure, to construct a neighbor of the current solution, a customer is removed from its route and inserted to a different position in the same route or another route planned at the same period. In Figure 2, customer 3 is moved from the route (1) to route (2) at the same period. In this structure, a neighbor of the current solution is obtained by swapping a customer of one route by a customer of another route at the same period. For example, in Figure 3, customer 8 from the route (2) is exchanged by customer 3 from the route (1) at the same period.

A neighbor of the solution is gained by removing a customer of a route. It means that the demand of the removed customer is delivered in the previous periods. Therefore, the transportation cost will decrease and the inventory costs will increase. For example, as it is shown in Figure 4, customer 8 is removed from the route (1).

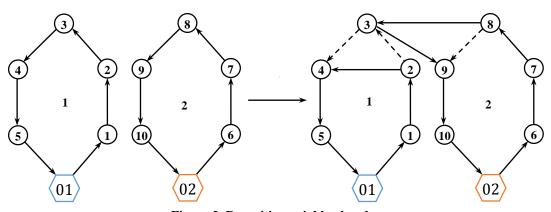


Figure 2. Reposition neighborhood

# Swap Neighborhood (E2)

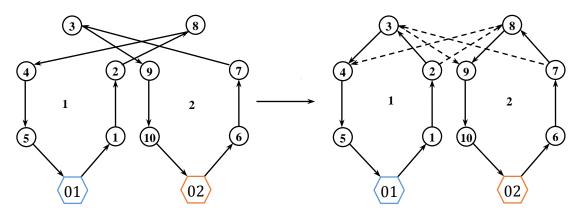


Figure 3. Swap neighborhood

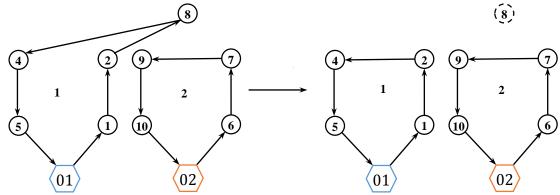


Figure 4.Remove Neighborhood

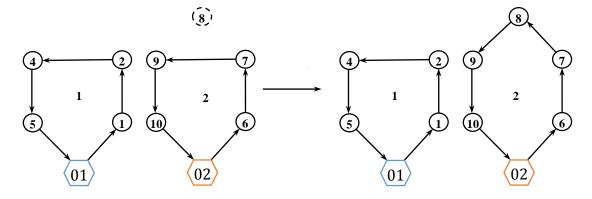


Figure 5. Add neighborhood

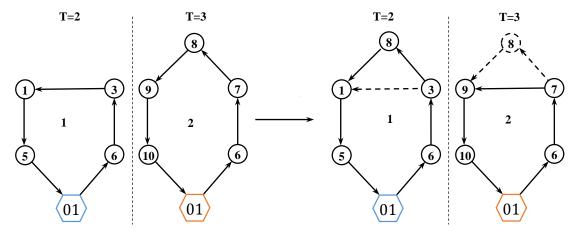


Figure 6. Drop neighborhood

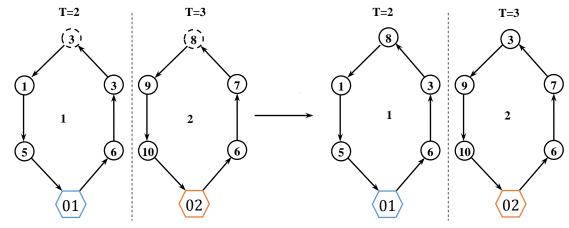


Figure 7.Swap Periodic Neighborhood

### Remove Neighborhood (E<sub>3</sub>)

The difference between Drop neighborhood and Remove neighborhood is that in the latter, the demand of the customer which is removed is satisfied in the nearest previous period visited but in the first, the demand of the customer which is removed is satisfied exactly in the previous period.

#### **Swap Periodic Neighborhood (E6)**

A neighbor of a solution is obtained by swapping two customers of two routes in different periods. For example, in Figure 7, customer 8 in route (2) and period 3 is swapped by customer 3 in the route (1) and period 2.

#### **Local Search Algorithm**

Since no further improvement occurs in the previous section, it might have fallen into the

local optimality., some heuristic local search methods are used for escaping this trap. Arc exchange, Depot Exchange, and Partial Route Drop are three heuristic method which are used in this section. More details are described as follows:

#### **Arc Exchange**

In this procedure a neighbor of the current solution is obtained by exchanging an arc of one route by an arc of another route at the same period. For example, in Figure 8, the arc between customer 9 and customer 10 from the route (1) is exchanged by the arc between customer 1 and customer 2 from the route (2) at the same period.

In this procedure, a neighbor of the current solution is achieved by swapping the depot of one route by the depot of another route at the same period. Similarly, all possible exchange modes are checked.

### **Drop Partial Route**

In this heuristic procedure, a neighbor of the solution is defined by removing partial customers of a route and adding them to a new position in another route at the same period. For example, in Figure 9, customers 1 and 2 are removed from the route (1) and are inserted into the route (2).

#### **Depot Exchange**

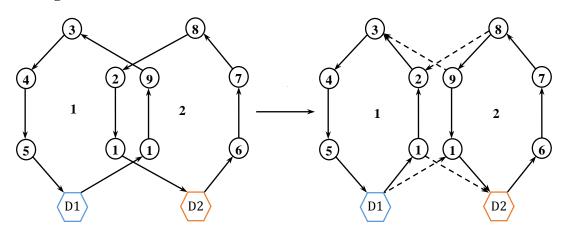


Figure 8. Arc exchange neighborhood

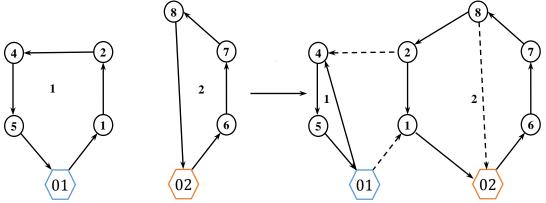


Figure 9. Drop Partial Route

#### 4. Computational results

Our proposed algorithm was coded in MATLAB 2014.b and computational experiments were conducted on a platform Intel Core i5 with 4 GB RAM and 3.4 GHz processor. Detailed experimental tests were presented for the introduced algorithm. Due to randomness nature of our proposed method, five independent replications were run on each instance and the minimum objective value among the five runs is reported.

To evaluate the quality of our proposed heuristic method, two benchmark datasets are employed for the single-depot and multivehicle case generated by Archetti et al. [Archetti et al, 2007] and the obtained results are compared with some available results in the literature including Coelho & Laporte [Coelho & Laporte, 2013] and Adulyasak et al. [Adulyasak et al. 2014]. These data sets are

classified by the number of customers and the planning horizon. In addition, they are divided into two sets with respect to two levels of inventory holding costs. It is included six time periods with 30 customers, and three time periods with 50 customers. These are characterized small-n-p-low or small-n-p-high in which n represent the number of customers, p represents the number of periods and symbol low/high is about two levels of inventory holding costs. The solution results are reported in Table 1 and Table 2. The first column demonstrates the instance names. Then, , the tables provide a gap of the best cost obtained in five runs of each algorithm in comparison with the best lower bound (LB) obtained by Coelho et.al [Coelho et. al., 2012] and the duration of the best run in seconds. For example, the deviation of a method A to the LB is computed as:

$$Gap(\%) = (Cost(A) - LB/LB) * 100$$

Table 1. Computational results on the (Coelho & Laporte 2013)small instances set, p=3.

·				K=2					K	=3			
instances	Our al	Our algorithm		(Coelho & Laporte 2013)		(Adulyasak et al. 2014)		Our algorithm		(Coelho & Laporte 2013)		(Adulyasak et al. 2014)	
	Gap %	Cpu(s)	Gap%	Cpu (s)	Gap%	Cpu (s)	Gap%	Cpu(s)	Gap %	Cpu(s)	Gap%	Cpu(s)	
Small-5-low	0.00	45.6	0.00	3.8	0.00	0.1	0.00	56.8	0.00	4.6	0.00	0.3	
Small-10-low	0.00	83.5	0.00	7.6	0.00	1.2	0.00	89.8	0.00	17.4	0.00	6.7	
Small-15-low	0.00	123.8	0.00	11.8	0.00	3.3	0.00	127.5	0.00	31.4	0.00	29.2	
Small-20-low	0.00	166.3	0.00	24.4	0.00	21.1	0.00	179.9	0.00	220.8	0.00	237.7	
Small-25-low	0.00	207.2	0.00	31.6	0.00	55.7	0.00	229.6	0.00	574.2	0.00	639.9	
Small-30-low	0.00	244.3	0.00	61.8	-	-	0.00	281.6	0.00	1285.8	0.00	1746.9	
Small-35-low	0.70	282.8	0.00	56.0	-	-	0.00	333.1	0.00	1935.8	0.00	2224.3	
Small-40-low	1.10	391.4	0.00	525.0	-	-	0.90	447.3	0.00	9092.0	0.00	5569.1	
Small-45-low	0.90	513.4	0.00	3867.8	-	-	1.90	588.0	0.86	31805	0.00	18549	
Small-50-low	1.70	900.2	0.15	10796.3	-	-	4.90	1002.7	12.40	42930	4.9	43200	
Small-5-high	0.00	43.8	0.00	2.8	0.15	0.2	0.00	40.1	0.00	2.3	0.00	0.3	
Small-10-high	0.00	89.5	0.00	5.8	0.00	1.2	0.00	79.7	0.00	12.6	0.00	7.6	
Small-15-high	0.00	135.1	0.00	11.6	0.00	3.3	0.00	123.9	0.00	26.0	0.00	24.7	
Small-20-high	0.00	172.6	0.00	23.8	0.00	17.3	0.00	171.4	0.00	217.4	0.00	227.6	
Small-25-high	0.90	209.3	0.00	30.8	0.00	31.1	0.00	215.1	0.00	1013.6	0.00	646.1	
Small-30-high	1.00	248.5	0.00	70.4	-	-	0.00	268.8	0.00	1623.4	0.00	966.9	
Small-35-high	0.80	285.6	0.00	65.6	-	-	0.00	332.2	0.00	2696.0	0.00	1624	
Small-40-high	0.20	424.5	0.00	478.5	-	-	0.81	451.3	0.00	6312.4	0.00	5638	
Small-45-high	1.90	542.2	0.00	1595.0	-	-	1.20	597.0	0.4	32820	0.00	13913	
Small-50-high	2.10	933.8	0.00	4431.6	-	-	1.90	1017.7	4.39	42990	1.5	43200	
Average	0.56	302.17	0.07	1105.1	-	-	0.58	330.925	0.90	8780.5	0.32	6922.6	

				K=2			K=3						
instances	Our alg	Our algorithm		(Coelho & Laporte 2013)		Adulyasak et.al [*]		Our algorithm		(Coelho & Laporte 2013)		(Adulyasak et al. 2014)	
	Gap%	Cpu	Gap%	Cpu	Gap%	Cpu	Gap%	Cpu	Gap %	Cpu	Gap%	Cpu	
Small-5-low	0.00	210.4	0.00	9.0	0.00	2.5	0.00	219.1	0.00	56.6	0.00	94.7	
Small-10-low	0.00	365	0.00	607.4	0.00	86.2	0.80	405.1	0.98	14578	0.50	15658	
Small-15-low	0.00	525	0.00	555.2	0.00	451.0	0.56	571.3	0.36	18761	0.80	20951	
Small-20-low	0.00	850	0.00	8642.4	0.00	2542.6	0.47	919.1	7.11	42751	8.20	43200	
Small-25-low	0.61	1055	0.24	19002	0.00	12045.5	6.87	1155.0	8.76	43047	10.00	43200	
Small-30-low	1.20	1339	1.74	36841	-	-	11.96	1411.5	12.52	43047	-	-	
Small-5-high	0.00	221	0.00	9.0	0.00	2.3	0.00	223.3	0.00	38.0	0.00	60.0	
Small-10-high	0.00	401	0.00	57.6	0.00	70.2	0.60	433.9	0.71	14611	0.60	16801	
Small-15-high	0.00	571	0.00	351.0	0.00	408.0	0.52	603.9	0.48	12470	0.20	16821	
Small-20-high	0.00	907	0.00	4035.8	0.00	1932.5	3.89	933.2	3.82	42985	3.80	40411	
Small-25-high	0.00	1085	0.00	10160	0.00	10160.2	4.62	1145.0	4.58	39241	4.80	43200	
Small-30-high	0.80	1350	0.67	28788	-	-	5.83	1424.6	6.20	42963	-	-	
Average	0.22	739.9	0.22	9088.2	-	-	3.01	787.1	3.79	26212.4	-	-	

Table 2. Computational results on the (Coelho & Laporte 2013)small instances set, p=6.

The first row shows the number of vehicles for each instance. The last row displays the average gap and the mean CPU time for each algorithm. Numbers in boldface indicate which methods give the same LB.

As it can be seen in Table 1, for k=2, the average of gaps obtained by Coelho & Laporte [Coelho & Laporte, 2013] is lower than what is obtained in this study. But their solution time's average is much more than the proposed method. For k=3, the average of gaps of the proposed method is lower than the one obtained by Coelho et.al [Coelho et al. 2013] but is more than the average obtained by Adulyasak et al. [Adulyasak et al. 2014].

In Table 2, for k=2, the average of gaps obtained by Coelho and Laporte [Coelho and Laporte, 2013] appear to be the same as the proposed method. However, solution time's average obtained by these authors is much more than the proposed method. For k=3, the average of gaps of the proposed method is the

same as the one obtained by Coelho and Laporte [Coelho and Laporte, 2013].

In the second set of the experiments, new instances for the case with multiple depots have been generated. In these sets of instances, modifying the instances proposed by Coelho et al. [Coelho et al, 2012] were obligated. In order to solve the multiple depots IRP, the same algorithm used in the previous section was applied. Also a simulated annealing algorithm was applied to solve the multi-depot IRP. In Tables 3-4 the comparison between our two-phase VNS-SA algorithms with the proposed SA method is provided. Note that "BKS" in the presented tables represent the best-known solution which has been founded in the current level of problem.

Tables 3-4 present the average solutions of these strategies over ten runs for the proposed instances. Similarly, in these tables, different combinations of the parameters such as the

planning horizons T=3 and 6 and the number of vehicles K=2 and 3 are presented. In each table, the average percentage gap is demonstrated. Comparing the results obtained by the proposed method with SA algorithm has quite interesting results. Two-phase VNS-SA finds a better solution than SA and the average gap for the two-phase VNS-SA is obviously lower.

In Tables 5-6, it has been tried to reflect the effect of a set of local searches used in the

proposed algorithm. For this purpose, a comparison between solutions under the local searches and without them for the multidepot IRP is provided. The average gap between the two mentioned strategies in the same tables is reported to One considerable point is that the algorithm stops when the solutions will not be improved by local searches either. Therefore, the reported gap describes the solution improvement percentage via local searches.

Table 3. Computational results on the small instances set for MDMVIRP, p=3.

	-		K=2					K=3		
instances	BKS	Our alg	gorithm	-	SA		Our algorithm		SA	
	DK3	Gap %	Cpu(s)	Gap%	Cpu (s)	BKS	Gap%	Cpu(s)	Gap %	Cpu(s)
Small-5-low	1446.49	0.00	50.2	0.00	54.7	1727.54	0.00	62.5	0.00	68.1
Small-10-low	2137.97	0.00	91.9	0.00	100.2	2480.00	0.00	98.8	0.00	107.7
Small-15-low	2282.68	0.00	136.2	0.00	148.5	2503.63	0.00	140.3	0.00	152.9
Small-20-low	2745.29	0.00	182.9	0.09	199.4	3010.91	0.00	197.9	0.08	215.7
Small-25-low	2969.01	0.00	227.9	0.10	248.4	3247.20	0.00	252.6	0.09	275.3
Small-30-low	3134.84	0.00	268.7	0.08	292.9	3307.91	0.00	309.8	0.10	337.7
Small-35-low	3277.72	0.00	311.1	0.12	339.1	3520.04	0.00	366.4	0.09	399.4
Small-40-low	3488.58	0.00	430.5	0.10	469.2	3605.50	0.00	492.0	0.07	536.3
Small-45-low	3632.50	0.00	564.7	0.13	615.5	3745.48	0.00	646.8	0.13	705.0
Small-50-low	4018.78	0.00	990.2	0.08	1079.3	4259.22	0.00	1103.0	0.10	1202.3
Small-5-high	2270.12	0.00	48.2	0.00	52.5	2245.85	0.00	44.1	0.00	48.1
Small-10-high	4297.49	0.00	98.5	0.00	107.4	4590.71	0.00	87.7	0.00	95.6
Small-15-high	5134.05	0.00	148.6	0.07	162.0	5283.13	0.00	136.3	0.00	148.6
Small-20-high	6726.94	0.00	189.9	0.08	207.0	6910.83	0.00	188.5	0.09	205.5
Small-25-high	8174.42	0.00	230.2	0.11	250.9	8273.35	0.00	236.6	0.10	257.9
Small-30-high	9657.89	0.00	273.4	0.08	298.0	9619.92	0.00	295.7	0.08	322.3
Small-35-high	10000.78	0.00	314.2	0.10	342.5	10046.23	0.00	365.4	0.11	398.3
Small-40-high	10868.00	0.00	467.0	0.09	509.0	10833.22	0.00	496.4	0.08	541.1
Small-45-high	11890.25	0.00	596.4	0.12	650.1	11754.10	0.00	656.7	0.12	715.8
Small-50-high	13034.24	0.00	1027.2	0.10	1112.6	13025.87	0.00	1119.5	0.11	1220.3
Average	5559.40	0.00	332.4	0.07	332.4	5699.53	0.00	364.9	0.07	397.7

	-		K=2					K=3		
instances	DIZC	Our algorithm		SA		DIZC	Our algorithm		SA	
	BKS	Gap %	Cpu(s)	Gap%	Cpu (s)	BKS	Gap%	Cpu(s)	Gap %	Cpu(s)
Small-5-low	3380.69	0.00	238.1	0.00	255.3	4251.51	0.00	241.0	0.00	264.8
Small-10-low	4930.62	0.00	410.0	0.00	421.9	6043.56	0.00	445.6	0.00	467.6
Small-15-low	5410.22	0.00	588.4	0.08	602.1	6329.50	0.00	628.4	0.10	646.6
Small-20-low	6505.06	0.00	940.7	0.12	960.3	7614.64	0.00	1011.0	0.11	1030.9
Small-25-low	7064.88	0.00	1168.5	0.10	1182.2	8310.38	0.00	1270.5	0.09	1289.3
Small-30-low	7343.43	0.00	1480.8	0.11	1498.3	8253.32	0.00	1552.7	0.11	1575.3
Small-5-high	5231.71	0.00	249.7	0.00	262.1	6068.02	0.00	245.6	0.00	261.0
Small-10-high	8245.15	0.00	448.0	0.05	465.1	9196.61	0.00	477.3	0.07	497.1
Small-15-high	10471.86	0.00	634.1	0.10	655.2	11355.67	0.00	664.3	0.10	689.5
Small-20-high	13081.88	0.00	1003.6	0.09	1025.7	14035.68	0.00	1026.5	0.09	1046.9
Small-25-high	14755.89	0.00	1202.8	0.11	1219.9	15698.17	0.00	1259.5	0.10	1280.0
Small-30-high	17386.87	0.00	1490.6	0.12	1515.4	18150.18	0.00	1567.1	0.11	1596.7
Average	8650.69	0.00	162.2	0.07	838.6	9608.94	0.00	865.8	0.07	887.1

Table 4. Computational results on the small instances set for MDMVIRP, p=6.

#### 5. Conclusions

A hybrid heuristic algorithm based on the variable neighborhood search and the simulated annealing algorithm is introduced in this study. The proposed algorithm is comprised of two phases. The first phase generates an initial solution in which inventory costs are ignored in step 1. In the second phase the solution, which is initially constructed in phase 1, is improved by applying both a variable neighborhood search and local search. Six different a neighborhood structures and 3 different local searches for the proposed algorithm has been used in this study. The computational tests showed that this algorithm provides near optimal solution in the more reasonable time than the ones obtained by the existing method. The applications of such proposed model arise in a wide variety of industries such as the distribution of blood products, food distribution to supermarket chains, delivery of waste organic oil and etc. there are many issues which can enhance the models usage in these research area,. Some of the most significant issues are addressed as follows:

- Considering limited shelf life of products in the model (perishability)
- Transshipment between distribution centers and customers
- Developing the model by adding pickup and delivery constraints which leads to more realistic results.
- Solving model by another heuristic and meta-heuristic efficient algorithm and comparing with our experimental results

Table 5. Computational results of the effect of local search on the results, p=3.

			K=2		K=3						
instances	BKS	Our al	Our algorithm		VNS		Our algorithm		VNS		
	BKS	Gap %	Cpu(s)	Gap%	Cpu (s)	BKS	Gap%	Cpu(s)	Gap %	Cpu(s)	
Small-5-low	1446.49	0.00	50.2	0.00	57.7	1727.54	0.00	62.5	0.00	73.1	
Small-10-low	2137.97	0.00	91.9	0.00	105.7	2480.00	0.00	98.8	0.00	115.6	
Small-15-low	2282.68	0.00	136.2	4.00	156.6	2503.63	0.00	140.3	3.00	164.2	
Small-20-low	2745.29	0.00	182.9	3.00	210.3	3010.91	0.00	197.9	4.00	231.5	
Small-25-low	2969.01	0.00	227.9	8.00	262.1	3247.20	0.00	252.6	6.00	295.5	
Small-30-low	3134.84	0.00	268.7	6.00	309.0	3307.91	0.00	309.8	6.00	362.5	
Small-35-low	3277.72	0.00	311.1	9.00	357.8	3520.04	0.00	366.4	9.00	428.7	
Small-40-low	3488.58	0.00	430.5	8.00	495.1	3605.50	0.00	492.0	6.00	575.6	
Small-45-low	3632.50	0.00	564.7	9.00	649.4	3745.48	0.00	646.8	7.00	756.8	
Small-50-low	4018.78	0.00	990.2	6.00	1138.7	4259.22	0.00	1103.0	8.00	1290.5	
Small-5-high	2270.12	0.00	48.2	0.00	55.4	2245.85	0.00	44.1	0.00	51.6	
Small-10-high	4297.49	0.00	98.5	3.00	113.3	4590.71	0.00	87.7	0.00	102.6	
Small-15-high	5134.05	0.00	148.6	4.00	170.9	5283.13	0.00	136.3	4.00	159.5	
Small-20-high	6726.94	0.00	189.9	6.00	218.4	6910.83	0.00	188.5	3.00	220.5	
Small-25-high	8174.42	0.00	230.2	7.00	264.7	8273.35	0.00	236.6	8.00	276.8	
Small-30-high	9657.89	0.00	273.4	8.00	314.4	9619.92	0.00	295.7	8.00	346.0	
Small-35-high	10000.78	0.00	314.2	6.00	361.3	10046.23	0.00	365.4	9.00	427.5	
Small-40-high	10868.00	0.00	467.0	7.00	537.1	10833.22	0.00	496.4	8.00	580.8	
Small-45-high	11890.25	0.00	596.4	8.00	685.9	11754.10	0.00	656.7	9.00	768.3	
Small-50-high	13034.24	0.00	1027.2	10.00	1181.3	13025.87	0.00	1119.5	10.00	1309.8	
Average	5559.40	0.00	332.4	5.60	382.3	5699.53	0.00	364.9	5.40	426.9	

Table 6. Computational results of the effect of local search on the results, p=6.

	-		K=2		K=3					
instances	DVIC	Our algorithm			VNS		Our algorithm		VNS	
	BKS	Gap %	Cpu(s)	Gap%	Cpu (s)	BKS	Gap%	Cpu(s)	Gap %	Cpu(s)
Small-5-low	3380.69	0.00	238.1	0.00	259.5	4251.51	0.00	241.0	0.00	262.7
Small-10-low	4930.62	0.00	410.0	3.00	446.9	6043.56	0.00	445.6	4.00	485.7
Small-15-low	5410.22	0.00	588.4	7.00	641.4	6329.50	0.00	628.4	6.00	685.0
Small-20-low	6505.06	0.00	940.7	9.00	1025.4	7614.64	0.00	1011.0	8.00	1102.0
Small-25-low	7064.88	0.00	1168.5	8.00	1273.7	8310.38	0.00	1270.5	10.00	1384.8
Small-30-low	7343.43	0.00	1480.8	12.00	1614.1	8253.32	0.00	1552.7	9.00	1692.4
Small-5-high	5231.71	0.00	249.7	0.00	272.2	6068.02	0.00	245.6	0.00	267.7
Small-10-high	8245.15	0.00	448.0	6.00	488.3	9196.61	0.00	477.3	5.00	520.3
Small-15-high	10471.86	0.00	634.1	8.00	691.2	11355.67	0.00	664.3	7.00	724.1
Small-20-high	13081.88	0.00	1003.6	8.00	1093.9	14035.68	0.00	1026.5	7.00	1118.9
Small-25-high	14755.89	0.00	1202.8	7.00	1311.1	15698.17	0.00	1259.5	8.00	1372.9
Small-30-high	17386.87	0.00	1490.6	9.00	1624.8	18150.18	0.00	1567.1	10.00	1708.1
Average	8650.69	0.00	162.2	6.42	895.2	9608.94	0.00	865.8	6.17	943.7

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